



Frame	θ	β	α	ℓ
A	✓	✓	✓	✓
B	X	✓	✓	✓
C	X	X	✓	✓
D	X	X	X	✓

Vector Differentiation

$$\bar{r} = \ell \hat{a}_x$$

$$A \frac{\partial \bar{r}}{\partial \theta}$$

partial derivative of \bar{r} when observed from A with respect to θ

$$\bar{r} = \underbrace{a_1}_{\text{x component of } \bar{r}} \hat{a}_x + a_2 \hat{a}_y + \underbrace{a_3}_{\text{measure number of the z component of } \bar{r}} \hat{a}_z$$

$\hat{a}_x, \hat{a}_y, \hat{a}_z$ are fixed in A

$$A \frac{\partial \bar{r}}{\partial \theta} = \frac{\partial a_1}{\partial \theta} \hat{a}_x + \frac{\partial a_2}{\partial \theta} \hat{a}_y + \frac{\partial a_3}{\partial \theta} \hat{a}_z$$

$\frac{\partial \bar{r}}{\partial \theta}$ is meaningless if no frame is given!

If θ, β, α, l are all themselves functions of time

$\Rightarrow \theta(t), \beta(t), \alpha(t), l(t)$ time t is the single variable

$$\vec{r}(t) = a_1(t) \hat{a}_x + a_2(t) \hat{a}_y + a_3(t) \hat{a}_z$$

$$^A \frac{d\vec{r}}{dt} = \frac{da_1}{dt} \hat{a}_x + \frac{da_2}{dt} \hat{a}_y + \frac{da_3}{dt} \hat{a}_z$$

Dot notation

$$^A \dot{\vec{r}} = \dot{a}_1 \hat{a}_x + \dot{a}_2 \hat{a}_y + \dot{a}_3 \hat{a}_z$$

When the measure numbers are expressions containing functions of time, e.g. $\underline{\theta(t)}$, the chain rule can be used to calculate the derivative.

$$^A \frac{d\vec{r}}{dt} = \frac{\partial \vec{r}}{\partial \theta} \frac{d\theta}{dt} + \frac{\partial \vec{r}}{\partial \beta} \frac{d\beta}{dt} + \frac{\partial \vec{r}}{\partial \alpha} \frac{d\alpha}{dt} + \frac{\partial \vec{r}}{\partial l} \frac{dl}{dt} + \frac{\partial \vec{r}}{\partial t} \left\{ \begin{array}{l} \text{if } t \text{ is} \\ \text{explicit in} \\ \text{expressions} \end{array} \right.$$

Second (and higher) Derivatives

$$^B \frac{\partial}{\partial y} \left(^A \frac{\partial \vec{r}}{\partial x} \right) \neq ^A \frac{\partial}{\partial x} \left(^B \frac{\partial \vec{r}}{\partial y} \right)$$

$$\vec{q} = t \hat{a}_y \quad ^B \frac{d}{dt} \left(^A \frac{d\vec{q}}{dt} \right) = ?$$

$$^A \frac{d}{dt} \left(^B \frac{d\vec{q}}{dt} \right) = ?$$

incorrectly wrote in video as c